

# WEST Search History

DATE: Friday, September 19, 2008

<u>Hide?</u>	<u>Set Name</u>	<u>Query</u>	<u>Hit Count</u>
<i>DB=USPT; PLUR=YES; OP=ADJ</i>			
<input type="checkbox"/>	L49	foot and L48	14
<input type="checkbox"/>	L48	float\$4 and L47	15
<input type="checkbox"/>	L47	"0" and L46	67
<input type="checkbox"/>	L46	robot\$6 and L45	87
<input type="checkbox"/>	L45	L44 and zmp (700/245 l700/246 l700/251 l700/253 l700/260 l700/261 318/568.1 l 318/568.12 l318/568.16 l318/568.17 l318/568.2 901/1 l901/9 l901/46 180.1).ccls.	87
<input type="checkbox"/>	L43	(("6962220")!.PN.) .p67-p150.	1
<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>			
<input type="checkbox"/>	L42	robot\$6 and (walk\$3 or biped or humanoid or two legged) and (inlina\$6 or betn or tilt or deviat\$5 or obliqu\$5 or indirect\$4 or change direction or slope or slant)	5825
<input type="checkbox"/>	L41	('6711469' l'6697709' l'6567724' l'6505098' l'6493606' l'6480761' l'6330494' l'6289265' l'6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	16
<input type="checkbox"/>	L40	marc.xa. and legged and inclination	34
<input type="checkbox"/>	L39	marc.xa. and legged and inclinaiton	0
<input type="checkbox"/>	L38	('5404086')!.ABPN1,NRPN,PN,TBAN,WKU.	2
<input type="checkbox"/>	L37	(edditing or updating) and (motion or traject\$4 or movement) and zmp and robot\$6	23
<input type="checkbox"/>	L36	(edditing or updating) same (motion or traject\$4 or movement) and zmp and robot\$6	10
<input type="checkbox"/>	L35	(edditing or updating) same (motion or traject\$4 or movement) and L34	9
<input type="checkbox"/>	L34	robot and zmp and yaw	159
<input type="checkbox"/>	L33	marc.xa. and zmp	46
<input type="checkbox"/>	L32	10/181500	3

<input type="checkbox"/>	L31	('6697709' l'6289265' l'6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	6
<input type="checkbox"/>	L30	marc.xa. and robot and zmp	46
<input type="checkbox"/>	L29	(motions or movement or displacement) and L28	118
<input type="checkbox"/>	L28	computer and L27	130
<input type="checkbox"/>	L27	record\$3 and L26	130
<input type="checkbox"/>	L26	(request or command) and L25	156
<input type="checkbox"/>	L25	L21 and L24	163
<input type="checkbox"/>	L24	execut\$5 and L23	289586
<input type="checkbox"/>	L23	run or L21	1330102
		(6458772 or 6284156 or 6348461 or 6262044 or 6410586 or 6342245 or 6277877 or 6399557 or 3857856 or 5835892 or 6376445 or 6440911 or 6163111 or 5610305 or 5230889 or 4391489 or 4483594 or 6410749 or 4876009 or 6358945 or 6281227 or 6391397 or 6432994 or 4920120 or 5874378 or 6374641 or 5384779 or 5523998 or 5537098 or 4260406 or 4293439 or 4386503 or 5179438 or 5208607 or 6275216 or 5534261 or 5640119 or 5831440 or 6049212 or 6271251 or 4949326 or 5015815 or 5194938 or 4870247 or 6258470 or 6316465 or 6388989 or 4505827 or 5210848 or 5230070).pn.	98
<input type="checkbox"/>	L21	(similar or "same") function and L20	189
<input type="checkbox"/>	L20	robot and control software and (chang\$3 or replac\$5)	2026
<input type="checkbox"/>	L19	('20050125099')!.ABPN1,NRPN,PN,TBAN,WKU.	2
<input type="checkbox"/>	L18	(10/126774   10/970977   10/935607   10/919172   10/775845   10/732446   10/726597   10/683496   10/637890)	18
<input type="checkbox"/>	L17	(motion or displacement or trajector\$3) and L16	110
<input type="checkbox"/>	L16	(humanoid or two legged robot and human like robot) and zmp and comput\$5	113
<input type="checkbox"/>	L15	zmp and "approximately 0"	17
	<i>DB=PGPB,USPT; PLUR=YES; OP=ADJ</i>		
<input type="checkbox"/>	L14	(("20060106495")!.PN.) .PGPB.   (("7119510")!.PN.) .USPT.	2
	<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>		
<input type="checkbox"/>	L13	grasping and L12	6
<input type="checkbox"/>	L12	horizontal and vertical and L11	19
<input type="checkbox"/>	L11	signal and detection and L10	19
<input type="checkbox"/>	L10	distance and L9	22

<input type="checkbox"/>	L9	center and L8	27
<input type="checkbox"/>	L8	motion and L7	29
<input type="checkbox"/>	L7	gravity and L6	30
<input type="checkbox"/>	L6	floor reaction and l5	35
<input type="checkbox"/>	L5	foot and robot and ground contact and sensor and sole and joint and reaction and force and walk\$3	52
<i>DB=PGPB; PLUR=YES; OP=ADJ</i>			
<input type="checkbox"/>	L4	L3	1
<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>			
<input type="checkbox"/>	L3	10/553278	1
<input type="checkbox"/>	L2	L1 and robot	12
<input type="checkbox"/>	L1	metatarsophalangeal	507

END OF SEARCH HISTORY